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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/534,639	05/12/2005	Alan George Rock	P2481US	1659
8968 DRINKER BII	7590 05/07/2007 DDLE & REATH LLP		EXAMINER	
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Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

		Application No.	Applicant(s)
		10/534,639	ROCK ET AL.
	Office Action Summary	Examiner	Art Unit
		Tania C. Courson	2859
Period fo	The MAILING DATE of this communication app or Reply	ears on the cover sheet with the c	orrespondence address
A SH WHIC - Exter after - If NC - Failu Any I	ORTENED STATUTORY PERIOD FOR REPLY CHEVER IS LONGER, FROM THE MAILING DANS IN THE MAILING DANS IN THE MORE IN THE MAILING DANS IN (6) MONTHS from the mailing date of this communication. In period for reply is specified above, the maximum statutory period were to reply within the set or extended period for reply will, by statute, reply received by the Office later than three months after the mailing and patent term adjustment. See 37 CFR 1.704(b).	ATE OF THIS COMMUNICATION 16(a). In no event, however, may a reply be tim rill apply and will expire SIX (6) MONTHS from cause the application to become ABANDONEI	L. ely filed the mailing date of this communication. O (35 U.S.C. § 133).
Status			
2a)⊠	Responsive to communication(s) filed on <u>22 Fe</u> This action is FINAL . 2b) This Since this application is in condition for allowant closed in accordance with the practice under E	action is non-final.	
Dispositi	on of Claims		
5)□ 6)⊠ 7)□	Claim(s) <u>1-9,11,13,15,18-21,26,28 and 30-43</u> is 4a) Of the above claim(s) is/are withdraw Claim(s) is/are allowed. Claim(s) <u>1-9,11,13,15,18-21,26,28 and 30-43</u> is Claim(s) is/are objected to. Claim(s) are subject to restriction and/or	vn from consideration. s/are rejected.	
Applicati	on Papers		
10)⊠	The specification is objected to by the Examiner The drawing(s) filed on 12MAY05 & 22FEB07 is Applicant may not request that any objection to the conference Replacement drawing sheet(s) including the correction The oath or declaration is objected to by the Example 1.	s/are: a)⊠ accepted or b)⊡ object drawing(s) be held in abeyance. See on is required if the drawing(s) is obj	37 CFR 1.85(a). ected to. See 37 CFR 1.121(d).
Priority u	ınder 35 U.S.C. § 119		
a)[Acknowledgment is made of a claim for foreign All b) Some * c) None of: 1. Certified copies of the priority documents 2. Certified copies of the priority documents 3. Copies of the certified copies of the prioric application from the International Bureau see the attached detailed Office action for a list of	have been received. have been received in Application ity documents have been receive (PCT Rule 17.2(a)).	on No d in this National Stage
Attachmen	t(s) e of References Cited (PTO-892)	() The transfer Comment	(DTO 412)
2) Notic 3) Inform	e of References Cited (FTO-692) e of Draftsperson's Patent Drawing Review (PTO-948) nation Disclosure Statement(s) (PTO/SB/08) r No(s)/Mail Date	4) Interview Summary (Paper No(s)/Mail Da 5) Notice of Informal Pa	te

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DETAILED ACTION

Claim Rejections - 35 USC § 102

1. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless -

(b) the invention was patented or described in a printed publication in this or a foreign country or in public use or on sale in this country, more than one year prior to the date of application for patent in the United States.

2. Claims 1-9, 11, 13, 15, 18-21, 26-28 and 31-42 are rejected under 35 U.S.C. 102(b) as being anticipated by Davis (GB 2045938 A).

Davis disclose in the Figure, a measuring device comprising:

With respect to claims 1-4 and 31-42:

a) a housing (1), power supply means (page 1, lines 118-122), one or more motion sensors (7-12) adapted to detect motion in six degrees of freedom (7-12), a processor (14) adapted to provide a measure of the relative spatial separation (page 2, lines 63-80), a user actuated trigger (5) for identifying a first location and a display (15) for visually presenting information on a measured relative spatial separation (the Figure) said processor is adapted further to determine at least one angle of a second location with a reference to a line or plane incorporating said first location (page 2, lines 31-44) for presentation by said display (page 2, lines 63-80) and to determine an error correction in relation to motion detected by said one or more motion sensors (page 2, lines 116-120);

- b) wherein said processor is adapted to determine said at least one angle with respect to one or both of vertical and horizontal planes (page 2, lines 31-43);
- c) wherein said processor is adapted to determine whether said first and second locations are level with respect to either of said vertical or horizontal planes (page 2, lines 31-43);
- d) wherein said processor is adapted to determine, in addition to said at least one angle, a linear distance separating said first and second locations (page 2, lines 31-43);
- e) further comprising a measuring point (3) provided on said housing and having a defined spatial relationship with respect to said one or more motion sensors (the Figure), said measuring point being visually distinguishable on said housing and user alignable with a user selected spatial location (page 2, lines 31-43);
- f) wherein said measuring point is adapted to be substantially stationary when aligned by a user with a selected spatial location (page 2, lines 95-120);
- g) wherein the processor is adapted to determine an error correction when said measuring point is aligned with a selected spatial location and is substantially stationary, in relation to motion detected by said one or more motion sensors (page 2, lines 95-120);
- h) wherein the processor is in communication with a memory in which is stored calibration data and the processor is adapted to update calibration data stored in said memory at a second or subsequent location (page 2, lines 95-120);

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i) wherein said processor is adapted to adjust for movement of the one or more motion sensors as a result of uncontrolled hand movements of the user when updating calibration data stored in said memory (page 2, lines 95-120);

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- j) comprising a plurality of motion sensors comprising at least three accelerometers and three angular rate sensors (page 2, lines 74-80);
- k) further including a timer, in communication with the processor, for monitoring the time duration of a measurement wherein the processor is adapted to determine the measure of relative spatial separation to a resolution dependent upon the time duration of the measurement (page 1, lines 35-50);
- the processor is adapted to determine from information received from the motion sensors when the measuring device is stationary and to generate an error correction (page 2, lines 95-120);
- m) wherein the processor has access to threshold data identifying lower limits of measurable spatial movement representative of small, uncontrolled hand movements of a user (page 2, lines 95-120);
- n) further comprising a deceleration device for reducing high deceleration forces (page 2, lines 116-120);
- o) wherein the processor is adapted to supply real time data on the measured relative spatial separation (page 1, lines 35-50);
- p) wherein the processor additionally includes a data store in which motion data is stored and said processor is adapted to update said stored motion data in dependence on calculated error corrections or updated calibration data and to

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recalculate said measured spatial separation in dependence on the updated motion data (page 2, lines 95-120).

With respect to claim 5:

a) a housing (1), power supply means (page 1, lines 118-122), a processor (14) and one or more motion sensors (7-12) adapted to provide a measure of the relative spatial separation of at least first and second locations (page 2, lines 63-80), a user actuated trigger (5) for identifying at least said first location and a display (15) for visually presenting information on a measured relative spatial separation (the Figure) wherein said processor is further adapted to determine at least one angle of said second location with reference to a line or plane incorporating said first location and a linear distance (page 2, lines 31-44) for presentation by said display (page 2, lines 31-43) and to determine an error correction in relation to motion detected by said one or more motion sensors (page 2, lines 116-120);

With respect to claims 6-9, 11, 13, 15, 18-21 and 26-28:

a) a housing (1), power supply means (page 1, lines 118-122), a processor (14) and one or more motion sensors (7-12) adapted to provide a measure of the relative spatial separation of at least first and second locations (page 2, lines 63-80), a user actuated trigger (5) for identifying at least said first location and a display (15) for visually presenting information on a measured relative

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spatial separation (the Figure) said measuring device further including a measuring point (3) provided on said housing having a defined spatial relationship with respect to said one or more motion sensors (the Figure), said measuring point being provided for identification to said processor (the Figure), in association with said user actuated trigger, at least one of said first and second locations (page 2, lines 31-43) and said processor being adapted to determine an error correction in relation to motion detected by said one or more motion sensors (page 2, lines 116-120);

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- b) wherein said measuring point is visually distinguishable on said housing and user alignable with a user selected spatial location (page 2, lines 31-43);
- c) wherein said measuring point is adapted to be substantially stationary when aligned by a user with a selected spatial location (the Figure);
- wherein processor is adapted to determine an error correction when said measuring point is aligned with a selected spatial location and is substantially stationary, in relation to motion detected by said one or more motion sensors (page 2, lines 95-120);
- e) wherein the processor is in communication with a volatile memory in which is stored calibration data and the processor is adapted to update calibration data stored in said volatile memory at a second or subsequent location (page 2, lines 95-120);

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f) wherein said processor is adapted for movement of the one or more motion sensors as a result of uncontrolled hand movements of the user when updating calibration data stored in said volatile memory (page 2, lines 95-120);

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- g) wherein said one or more motion sensors comprise at least three accelerometers and three angular rate sensors (page 2, lines 74-80);
- h) further including a timer, in communication with the processor for monitoring the time duration of a measurement wherein the processor is adapted to determine the measure of relative spatial separation to a resolution dependent upon the time duration of the measurement (page 1, lines 35-50);
- i) wherein the processor is adapted to determine from information received from the motion sensors when the measuring device is stationary and to generate an error correction (page 2, lines 95-120);
- j) wherein the processor has access to threshold data identifying lower limits of measurable spatial movement representative of small, uncontrolled hand movements of a user (page 2, lines 95-120);
- k) further comprising a deceleration device for reducing high deceleration forces (page 2, lines 116-120);
- l) wherein the processor is adapted to supply real time data on the measured relative spatial separation (page 1, lines 35-50);
- m) wherein the processor additionally includes a data store in which motion data is stored and said processor is adapted to update said stored motion data in dependence on calculated error corrections or updated calibration data and to

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recalculate said measured spatial separation in dependence on the updated motion data (page 2, lines 95-120).

With respect to the preamble of the claims 1 and 5-6: the preamble of the claim has not been given any patentable weight because it has been held that a preamble is denied the effect of a limitation where the claim is drawn to a structure and the portion of the claim following the preamble is a self – contained description of the structure not depending for completeness upon the introductory clause. *Kropa v. Robie*, 88 USPQ 478 (CCPA 1951).

Claim Rejections - 35 USC § 103

- 3. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 4. Claim 30 and 43 are rejected under 35 U.S.C. 103(a) as being unpatentable over Davis in view of Richter (US 6,715,213 B2).

Davis discloses a measuring device, as stated above in paragraph 2.

Davis does not disclose including a non-contact distance meter for measuring a distance to a position remote from the measuring device, the position being at least one of said first and second locations.

Richter teaches an analysis sample device that consists of including a non-contact distance meter (34) for measuring a distance to a position remote from the measuring device, the position being at least one of said first and second locations (column 4, lines 20-37). Therefore, it would have been obvious to one having ordinary skill in the art at the time the invention was made to further modify the measuring device of Davis, so as to include a non-contact distance meter, as taught by Richter, in order to increase precision when measuring a distant position.

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Response to Arguments

- 5. Applicant's arguments filed on February 22, 2007 have been considered but are moot in view of the new ground(s) of rejection.
- 6. With respect to the applicant's argument concerning the lack of "error correction" teaching in Davis, motion damping is an "error correction" component, thus Davis does teach this portion of the claim language.
- 7. With regards to the argument that Richter fails to teach "error correction", the applicant is improperly interpreting the Richter reference, as interpreted by the Examiner as provided in the prior office action. The Davis reference is the one that teaches the "error correction" portion of the claim language.

Conclusion

8. Applicant's amendment necessitated the new ground(s) of rejection presented in this Office action. Accordingly, **THIS ACTION IS MADE FINAL**. See MPEP § 706.07(a). Applicant is reminded of the extension of time policy as set forth in 37 CFR 1.136(a).

A shortened statutory period for reply to this final action is set to expire THREE MONTHS from the mailing date of this action. In the event a first reply is filed within TWO MONTHS of the mailing date of this final action and the advisory action is not mailed until after the end of the THREE-MONTH shortened statutory period, then the shortened statutory period will expire on the date the advisory action is mailed, and any extension fee pursuant to 37 CFR 1.136(a) will be calculated from the mailing date of the advisory action. In no event, however, will the statutory period for reply expire later than SIX MONTHS from the date of this final action.

9. Any inquiry concerning this communication or earlier communications from the examiner should be directed to Tania C. Courson whose telephone number is (571) 272-2239. The examiner can normally be reached on Monday, Wednesday and Thursday from 9AM to 5PM.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Diego Gutierrez, can be reached on (571) 272-2245.

The fax number for this Organization where this application or proceeding is assigned is (571) 273-8300.

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Information regarding the status of an application may be obtained from the Patent

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system, see http://pair-direct.uspto.gov. Should you have questions on access to the Private PAIR

system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

Diego Gutierrez
Supervisory Patent Examinar

Technology Cer

TCC

April 30, 2007